

参考 具体的なラプラシアン の 計算

$\frac{\partial^2 \varphi}{\partial x^2}$ は、

$$\begin{aligned}
 \frac{\partial^2 \varphi}{\partial x^2} &= \frac{\partial}{\partial x} \frac{\partial \varphi}{\partial x} \\
 &= \frac{\partial \frac{\partial \varphi}{\partial x}}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial \frac{\partial \varphi}{\partial x}}{\partial \theta} \frac{\partial \theta}{\partial x} + \frac{\partial \frac{\partial \varphi}{\partial x}}{\partial \phi} \frac{\partial \phi}{\partial x} \\
 &= \frac{\partial(\sin \theta \cos \phi \frac{\partial \varphi}{\partial r} + \frac{1}{r} \cos \theta \cos \phi \frac{\partial \varphi}{\partial \theta} - \frac{1}{r} \frac{\sin \phi}{\sin \theta} \frac{\partial \varphi}{\partial \phi})}{\partial r} \sin \theta \cos \phi \\
 &\quad + \frac{\partial(\sin \theta \cos \phi \frac{\partial \varphi}{\partial r} + \frac{1}{r} \cos \theta \cos \phi \frac{\partial \varphi}{\partial \theta} - \frac{1}{r} \frac{\sin \phi}{\sin \theta} \frac{\partial \varphi}{\partial \phi})}{\partial \theta} \frac{\cos \theta \cos \phi}{r} \\
 &\quad - \frac{\partial(\sin \theta \cos \phi \frac{\partial \varphi}{\partial r} + \frac{1}{r} \cos \theta \cos \phi \frac{\partial \varphi}{\partial \theta} - \frac{1}{r} \frac{\sin \phi}{\sin \theta} \frac{\partial \varphi}{\partial \phi})}{\partial \phi} \frac{\sin \phi}{r \sin \theta} \\
 &= \left[\sin \theta \cos \phi \frac{\partial^2 \varphi}{\partial r^2} + \cos \theta \cos \phi \left(-\frac{1}{r^2} \frac{\partial \varphi}{\partial \theta} + \frac{1}{r} \frac{\partial^2 \varphi}{\partial \theta \partial r} \right) \right. \\
 &\quad \left. - \frac{\sin \phi}{\sin \theta} \left(-\frac{1}{r^2} \frac{\partial \varphi}{\partial \phi} + \frac{1}{r} \frac{\partial^2 \varphi}{\partial \phi \partial r} \right) \right] \sin \theta \cos \phi \\
 &\quad + \left[\cos \phi \left(\cos \theta \frac{\partial \varphi}{\partial r} + \sin \theta \frac{\partial^2 \varphi}{\partial r \partial \theta} \right) + \frac{1}{r} \cos \phi \left(-\sin \theta \frac{\partial \varphi}{\partial \theta} + \cos \theta \frac{\partial^2 \varphi}{\partial \theta^2} \right) \right. \\
 &\quad \left. - \frac{1}{r} \sin \phi \left(-\frac{\cos \theta}{\sin^2 \theta} \frac{\partial \varphi}{\partial \phi} + \frac{1}{\sin \theta} \frac{\partial^2 \varphi}{\partial \phi \partial \theta} \right) \right] \frac{\cos \theta \cos \phi}{r} \\
 &\quad + \left[-\sin \theta \left(-\sin \phi \frac{\partial \varphi}{\partial r} + \cos \phi \frac{\partial^2 \varphi}{\partial r \partial \phi} \right) - \frac{1}{r} \cos \theta \left(-\sin \phi \frac{\partial \varphi}{\partial \theta} + \cos \phi \frac{\partial^2 \varphi}{\partial \theta \partial \phi} \right) \right. \\
 &\quad \left. + \frac{1}{r} \frac{1}{\sin \theta} \left(\cos \phi \frac{\partial \varphi}{\partial \phi} + \sin \phi \frac{\partial^2 \varphi}{\partial \phi^2} \right) \right] \frac{\sin \phi}{r \sin \theta} \\
 &= \sin^2 \theta \cos^2 \phi \frac{\partial^2 \varphi}{\partial r^2} + (\cos^2 \theta \cos^2 \phi + \sin^2 \phi) \frac{1}{r} \frac{\partial \varphi}{\partial r} \\
 &\quad + \frac{1}{r^2} \left[(-2 \cos \theta \sin \theta \cos^2 \phi + \frac{\cos \theta}{\sin \theta} \sin^2 \phi) \frac{\partial \varphi}{\partial \theta} + \cos^2 \theta \cos^2 \phi \frac{\partial^2 \varphi}{\partial \theta^2} \right. \\
 &\quad \left. + \left(\sin \phi \cos \phi + \frac{\sin \phi \cos \phi \cos^2 \theta}{\sin^2 \theta} + \frac{\cos \phi \sin \phi}{\sin^2 \theta} \right) \frac{\partial \varphi}{\partial \phi} + \frac{\sin^2 \phi}{\sin^2 \theta} \frac{\partial^2 \varphi}{\partial \phi^2} \right] \\
 &\quad + \frac{2}{r} \left[\cos \theta \sin \theta \cos^2 \phi \frac{\partial^2 \varphi}{\partial r \partial \theta} - \sin \phi \cos \phi \frac{\partial^2 \varphi}{\partial r \partial \phi} - \frac{1}{r} \frac{\cos \theta}{\sin \theta} \sin \phi \cos \phi \frac{\partial^2 \varphi}{\partial \theta \partial \phi} \right]
 \end{aligned}$$

(9.20)

となります。同様にして $\frac{\partial^2 \varphi}{\partial y^2}$ は、

$$\begin{aligned}
 \frac{\partial^2 \varphi}{\partial y^2} &= \frac{\partial}{\partial y} \frac{\partial \varphi}{\partial y} \\
 &= \frac{\partial \frac{\partial \varphi}{\partial y}}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial \frac{\partial \varphi}{\partial y}}{\partial \theta} \frac{\partial \theta}{\partial y} + \frac{\partial \frac{\partial \varphi}{\partial y}}{\partial \phi} \frac{\partial \phi}{\partial y} \\
 &= \frac{\partial \left(\sin \theta \sin \phi \frac{\partial \varphi}{\partial r} + \frac{1}{r} \cos \theta \sin \phi \frac{\partial \varphi}{\partial \theta} + \frac{1}{r} \frac{\cos \phi}{\sin \theta} \frac{\partial \varphi}{\partial \phi} \right)}{\partial r} \sin \theta \sin \phi \\
 &\quad + \frac{\partial \left(\sin \theta \sin \phi \frac{\partial \varphi}{\partial r} + \frac{1}{r} \cos \theta \sin \phi \frac{\partial \varphi}{\partial \theta} + \frac{1}{r} \frac{\cos \phi}{\sin \theta} \frac{\partial \varphi}{\partial \phi} \right) \cos \theta \sin \phi}{\partial \theta} \frac{\cos \theta \sin \phi}{r} \\
 &\quad + \frac{\partial \left(\sin \theta \sin \phi \frac{\partial \varphi}{\partial r} + \frac{1}{r} \cos \theta \sin \phi \frac{\partial \varphi}{\partial \theta} + \frac{1}{r} \frac{\cos \phi}{\sin \theta} \frac{\partial \varphi}{\partial \phi} \right) \cos \phi}{\partial \phi} \frac{\cos \phi}{r \sin \theta} \\
 &= \left[\sin \theta \sin \phi \frac{\partial^2 \varphi}{\partial r^2} + \cos \theta \sin \phi \left(-\frac{1}{r^2} \frac{\partial \varphi}{\partial \theta} + \frac{1}{r} \frac{\partial^2 \varphi}{\partial \theta \partial r} \right) \right. \\
 &\quad \left. + \frac{\cos \phi}{\sin \theta} \left(-\frac{1}{r^2} \frac{\partial \varphi}{\partial \phi} + \frac{1}{r} \frac{\partial^2 \varphi}{\partial \phi \partial r} \right) \right] \sin \theta \sin \phi \\
 &\quad + \left[\sin \phi \left(\cos \theta \frac{\partial \varphi}{\partial r} + \sin \theta \frac{\partial^2 \varphi}{\partial r \partial \theta} \right) + \frac{1}{r} \sin \phi \left(-\sin \theta \frac{\partial \varphi}{\partial \theta} + \cos \theta \frac{\partial^2 \varphi}{\partial \theta^2} \right) \right. \\
 &\quad \left. + \frac{1}{r} \cos \phi \left(-\frac{\cos \theta}{\sin^2 \theta} \frac{\partial \varphi}{\partial \phi} + \frac{1}{\sin \theta} \frac{\partial^2 \varphi}{\partial \phi \partial \theta} \right) \right] \frac{\cos \theta \sin \phi}{r} \\
 &\quad + \left[\sin \theta \left(\cos \phi \frac{\partial \varphi}{\partial r} + \sin \phi \frac{\partial^2 \varphi}{\partial r \partial \phi} \right) + \frac{1}{r} \cos \theta \left(\cos \phi \frac{\partial \varphi}{\partial \theta} + \sin \phi \frac{\partial^2 \varphi}{\partial \theta \partial \phi} \right) \right. \\
 &\quad \left. + \frac{1}{r} \frac{1}{\sin \theta} \left(-\sin \phi \frac{\partial \varphi}{\partial \phi} + \cos \phi \frac{\partial^2 \varphi}{\partial \phi^2} \right) \right] \frac{\cos \phi}{r \sin \theta} \\
 &= \sin^2 \theta \sin^2 \phi \frac{\partial^2 \varphi}{\partial r^2} + (\cos^2 \theta \sin^2 \phi + \cos^2 \phi) \frac{1}{r} \frac{\partial \varphi}{\partial r} \\
 &\quad + \frac{1}{r^2} \left[(-2 \cos \theta \sin \theta \sin^2 \phi + \frac{\cos \theta}{\sin \theta} \cos^2 \phi) \frac{\partial \varphi}{\partial \theta} + \cos^2 \theta \sin^2 \phi \frac{\partial^2 \varphi}{\partial \theta^2} \right. \\
 &\quad \left. - \left(\cos \phi \sin \phi + \frac{\cos \phi \sin \phi \cos^2 \theta}{\sin^2 \theta} + \frac{\sin \phi \cos \phi}{\sin^2 \theta} \right) \frac{\partial \varphi}{\partial \phi} + \frac{\cos^2 \phi}{\sin^2 \theta} \frac{\partial^2 \varphi}{\partial \phi^2} \right] \\
 &\quad + \frac{2}{r} \left[\cos \theta \sin \theta \sin^2 \phi \frac{\partial^2 \varphi}{\partial r \partial \theta} + \sin \phi \cos \phi \frac{\partial^2 \varphi}{\partial r \partial \phi} + \frac{1}{r} \frac{\cos \theta}{\sin \theta} \sin \phi \cos \phi \frac{\partial^2 \varphi}{\partial \theta \partial \phi} \right]
 \end{aligned} \tag{9.21}$$

となります。同様にして $\frac{\partial^2 \varphi}{\partial z^2}$ は、

$$\begin{aligned}
\frac{\partial^2 \varphi}{\partial z^2} &= \frac{\partial}{\partial z} \frac{\partial \varphi}{\partial z} \\
&= \frac{\partial}{\partial r} \frac{\partial \varphi}{\partial z} \frac{\partial r}{\partial z} + \frac{\partial}{\partial \theta} \frac{\partial \varphi}{\partial z} \frac{\partial \theta}{\partial z} + \frac{\partial}{\partial \phi} \frac{\partial \varphi}{\partial z} \frac{\partial \phi}{\partial z} \\
&= \frac{\partial}{\partial r} \left(\cos \theta \frac{\partial \varphi}{\partial r} - \frac{1}{r} \sin \theta \frac{\partial \varphi}{\partial \theta} \right) \cos \theta - \frac{\partial}{\partial \theta} \left(\cos \theta \frac{\partial \varphi}{\partial r} - \frac{1}{r} \sin \theta \frac{\partial \varphi}{\partial \theta} \right) \frac{\sin \theta}{r} \\
&= \left[\cos \theta \frac{\partial^2 \varphi}{\partial r^2} - \sin \theta \left(-\frac{1}{r^2} \frac{\partial \varphi}{\partial \theta} + \frac{1}{r} \frac{\partial^2 \varphi}{\partial \theta \partial r} \right) \right] \cos \theta \\
&\quad + \left[\sin \theta \frac{\partial \varphi}{\partial r} - \cos \theta \frac{\partial^2 \varphi}{\partial r \partial \theta} \right] + \frac{1}{r} \left(\cos \theta \frac{\partial \varphi}{\partial \theta} + \sin \theta \frac{\partial^2 \varphi}{\partial \theta^2} \right) \frac{\sin \theta}{r} \\
&= \cos^2 \theta \frac{\partial^2 \varphi}{\partial r^2} + \sin^2 \theta \frac{1}{r} \frac{\partial \varphi}{\partial r} + \frac{1}{r^2} \left[2 \sin \theta \cos \theta \frac{\partial \varphi}{\partial \theta} + \sin^2 \theta \frac{\partial^2 \varphi}{\partial \theta^2} \right] - \frac{2}{r} \cos \theta \sin \theta \frac{\partial^2 \varphi}{\partial r \partial \theta}
\end{aligned} \tag{9.22}$$

となります。これで直交座標 x, y, z 座標での2階微分を極座標 r, θ, ϕ で表すことができたので、直交座標で表されたラプラシアンに φ をかけた式を極座標で表すと、式 (9.20)、(9.21)、(9.22) を使い、微分の項ごとにまとめていくと、以下ようになります。

$$\begin{aligned}
&\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} + \frac{\partial^2 \varphi}{\partial z^2} \\
&= \left(\sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi + \cos^2 \theta \right) \frac{\partial^2 \varphi}{\partial r^2} \\
&\quad + \left(\cos^2 \theta \cos^2 \phi + \sin^2 \phi + \cos^2 \theta \sin^2 \phi + \cos^2 \phi + \sin^2 \theta \right) \frac{1}{r} \frac{\partial \varphi}{\partial r} \\
&\quad + \left(\sin \phi \cos \phi + \frac{\sin \phi \cos \phi \cos^2 \theta}{\sin^2 \theta} + \frac{\cos \phi \sin \phi}{\sin^2 \theta} \right. \\
&\quad \quad \left. - \sin \phi \cos \phi - \frac{\sin \phi \cos \phi \cos^2 \theta}{\sin^2 \theta} - \frac{\cos \phi \sin \phi}{\sin^2 \theta} \right) \frac{1}{r^2} \frac{\partial \varphi}{\partial \phi} \\
&\quad + \left(\frac{\sin^2 \phi}{\sin^2 \theta} + \frac{\cos^2 \phi}{\sin^2 \theta} \right) \frac{1}{r^2} \frac{\partial^2 \varphi}{\partial \phi^2} \\
&\quad + \left(-2 \cos \theta \sin \theta \cos^2 \phi + \frac{\cos \theta}{\sin \theta} \sin^2 \phi \right. \\
&\quad \quad \left. - 2 \cos \theta \sin \theta \sin^2 \phi + \frac{\cos \theta}{\sin \theta} \cos^2 \phi + 2 \sin \theta \cos \theta \right) \frac{1}{r^2} \frac{\partial \varphi}{\partial \theta} \\
&\quad + \left(\cos^2 \theta \cos^2 \phi + \cos^2 \theta \sin^2 \phi + \sin^2 \theta \right) \frac{1}{r^2} \frac{\partial^2 \varphi}{\partial \theta^2} \\
&\quad + \frac{2}{r} \left[\left(\cos \theta \sin \theta \cos^2 \phi + \cos \theta \sin \theta \sin^2 \phi - \cos \theta \sin \theta \right) \frac{\partial^2 \varphi}{\partial r \partial \theta} \right. \\
&\quad \quad \left. + \left(-\sin \phi \cos \phi + \sin \phi \cos \phi \right) \frac{\partial^2 \varphi}{\partial r \partial \phi} + \left(-\frac{1}{r} \frac{\cos \theta}{\sin \theta} \sin \phi \cos \phi + \frac{1}{r} \frac{\cos \theta}{\sin \theta} \sin \phi \cos \phi \right) \frac{\partial^2 \varphi}{\partial \theta \partial \phi} \right] \\
&= \frac{\partial^2 \varphi}{\partial r^2} + \frac{2}{r} \frac{\partial \varphi}{\partial r} + \frac{1}{r^2} \left(\frac{\cos \theta}{\sin \theta} \frac{\partial \varphi}{\partial \theta} + \frac{\partial^2 \varphi}{\partial \theta^2} + \frac{1}{\sin^2 \theta} \frac{\partial^2 \varphi}{\partial \phi^2} \right)
\end{aligned} \tag{9.23}$$

つまり、極座標で表されたラプラシアンに φ をかけた式 $\Delta\varphi$ は、

$$\Delta\varphi = \frac{\partial^2\varphi}{\partial x^2} + \frac{\partial^2\varphi}{\partial y^2} + \frac{\partial^2\varphi}{\partial z^2} = \frac{\partial^2\varphi}{\partial r^2} + \frac{2}{r}\frac{\partial\varphi}{\partial r} + \frac{1}{r^2}\left(\frac{\cos\theta}{\sin\theta}\frac{\partial\varphi}{\partial\theta} + \frac{\partial^2\varphi}{\partial\theta^2} + \frac{1}{\sin^2\theta}\frac{\partial^2\varphi}{\partial\phi^2}\right) \quad (9.24)$$

となります。また、

$$\begin{aligned} \frac{1}{\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial\varphi}{\partial\theta}\right) &= \frac{1}{\sin\theta}\left(\cos\theta\frac{\partial\varphi}{\partial\theta} + \sin\theta\frac{\partial^2\varphi}{\partial\theta^2}\right) \\ &= \frac{\cos\theta}{\sin\theta}\frac{\partial\varphi}{\partial\theta} + \frac{\partial^2\varphi}{\partial\theta^2} \end{aligned} \quad (9.25)$$

なので、極座標で表されたラプラシアン φ にをかけた $\Delta\varphi$ を、

$$\frac{\partial^2\varphi}{\partial x^2} + \frac{\partial^2\varphi}{\partial y^2} + \frac{\partial^2\varphi}{\partial z^2} = \frac{\partial^2\varphi}{\partial r^2} + \frac{2}{r}\frac{\partial\varphi}{\partial r} + \frac{1}{r^2}\left(\frac{1}{\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial\varphi}{\partial\theta}\right) + \frac{1}{\sin^2\theta}\frac{\partial^2\varphi}{\partial\phi^2}\right) \quad (9.26)$$

と書くこともあります。これで式 (9.17) が得られました。

❖ 球対称ポテンシャルにおける極座標シュレーディンガー方程式の変数分離

この極座標で表されたシュレーディンガー方程式は一般には解くことは困難です。しかし、第5章で見たように原子、原子核などさまざまな場合において、ポテンシャルは角度依存性がなく、**球対称** $V(r)$ でした。実はポテンシャルが球対称 $V(r)$ ならば、本書で何度も出てきた変数分離法によって簡単になることが知られています。そこで、本書ではポテンシャルは球対称 $V(r)$ である場合のみを考えましょう。

極座標シュレーディンガー方程式でポテンシャルを球対称 $V(r)$ と置いた式、

$$-\frac{\hbar^2}{2m}\left[\frac{d^2\varphi}{dr^2} + \frac{2}{r}\frac{d\varphi}{dr} + \frac{1}{r^2}\left(\frac{1}{\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial\varphi}{\partial\theta}\right) + \frac{1}{\sin^2\theta}\frac{\partial^2\varphi}{\partial\phi^2}\right)\right] + V(r)\varphi = E\varphi \quad (9.27)$$